

# Exercises for Probabilistic Graphical Models

## Sheet No. 3

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### Due Date: 4th January

Hand in: by 11:59pm by email to Apratim Bhattacharyya (abhattach at mpi-inf mpg de). Begin the subject of your e-mails with [PGM.Exercise3]. You should specify your first and last name as well matriculation number on submission. Please send your source code and all your results in a short report as a pdf. Explain your observations in this report.

In this exercise you are introduced to Markov random fields and their application to image denoising. We solve

$$p(\text{true}|\text{noisy}) = p(T|N) = p(N|T)P(T) \quad (1)$$

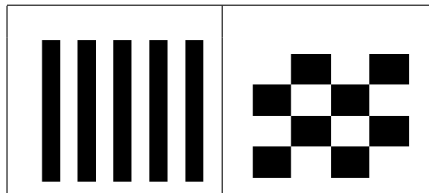
with gradient ascent method and compare our results to median filtering method. Finally, we have a look at different image priors  $p(T)$  and question the meaning of this priors as well as the independence assumption.

## 1 Evaluation

Before we start with image denoising, we need an evaluation framework that generates noisy images and calculates a performance measure to compare our algorithms.

**Tasks:** (2 points)

- Generate artificial images with binary pixel values  $x_{ij} \in \{0, 255\}$  that shows stripes (see left image), i.e.,



```
T = toy_stripes(n, m, sSize),
```

and a checkerboard pattern (right image), i.e.,

```
T = toy_checkerboard(n, m, cSize).
```

$T$  is the true image of size  $n \times m$  with stripe width  $sSize$  or black square size  $cSize$ .

- Write a function that adds Gaussian noise to an existing image  $T$ :

```
N = add_noise(T, sigma)
```

Also, write a function which adds salt and pepper noise (randomly occurring black and white pixels):

```
N = add_sp_noise(T, p)
```

- Write a function that calculates peak signal-to-noise ratio

$$PSNR = 20 \log_{10} \left( \frac{255}{\sqrt{err}} \right) \quad (2)$$

with reconstruction error  $err = (T - N)^2 / (nm)$ .

```
psnr = calc_psnr(T, N)
```

#### Hints:

- You can use matlab function `random()` with  $\mu = 0$  to add or subtract noise values from each pixel. Be sure that your pixel values are still in the range of  $[0, 255]$ .
- You should fix the random seed in your functions with Matlab function `RandStream`. This makes all results comparable to each other.

## 2 Median Filtering

A simple image denoising technique is median filtering. As you will find out, it often leads to blurred images.

#### Tasks: (3 points)

- Write a function `T = median_filter(N, nsize)` that replaces each pixel in a noisy image  $N$  with the median of the pixel values in a window of size  $nsize \times nsize$  around it. Take care at the image borders.
- Evaluate this denoising procedure on our different artificial examples with 10% salt'n'pepper noise and with the image `1a.png` downloadable from the course website after adding Gaussian noise with  $\sigma = 25$  (10% of the range). Show images before and after denoising and document PSNR for these images. What do you observe?
- Vary the amount of noise for the image `1a.png`.

### 3 MRF-based Denoising with Gradient Ascent

A better denoising technique is a MRF-based method with gradient ascent:

$$T^{t+1} \leftarrow T^t + \eta \nabla_T \log p(T|N) \quad (3)$$

with  $\log p(T|N) = \log p(N|T) + \log p(T) + \text{const}$ . *const* is ignored in all further computations as it doesn't depend on  $T$ . We need the gradient of both the likelihood  $\log p(N|T)$  and the prior  $\log p(T)$ . For simplicity, let's start with a Gaussian log-likelihood

$$\log p(N|T) = \sum_{i,j} \left( -\frac{1}{2\sigma^2} (N_{i,j} - T_{i,j})^2 \right), \quad (4)$$

as well as a Gaussian log-prior

$$\log p(T) = \sum_{i,j} \log(f_H(T_{i,j}, T_{i+1,j})) + \log(f_V(T_{i,j}, T_{i,j+1})) \quad (5)$$

with

$$\log f_H = -\frac{1}{2\sigma^2} (T_{i,j} - T_{i+1,j})^2 \quad (6)$$

for horizontal neighbors and  $\log f_V$  analogously.

**Tasks:** (8 points)

- Write a function  
`lp = denoising_lp(T, N, sigma)`  
to compute the log-posterior,  
`g = denoising_grad_llh(T, N, sigma)`  
to compute the gradient of the log likelihood  $\log p(N|T)$ , and  
`g = mrf_grad_log_gaussian_prior(T, sigma)`  
to calculate the gradient of the Gaussian prior  $\log p(T)$ .
- Finally, implement the gradient ascent to denoise the image  
`T = denoising_grad_ascent(N, sigma, eta)`.  
You should initialize the gradient ascent with the noisy image  $N$ .
- Explain your parameter tuning. Which observation do you make for different  $\sigma$  and  $\eta$ ? (See hints.)
- Evaluate your implementation with the noisy images from Task 2 for the same noise parameters. Check the PSNR and the increasing log-posterior curve. Compare your results with median filtering - which algorithm shows better results and why?

- What happens if you initialize gradient ascent with the output of median filtering? Is there an improvement in performance or a faster convergence observable?

**Hints:**

- The gradient `g` should have the same size as the input image while the log-posterior `lp` is just a scalar.
- You may need many iterations to reach approximate convergence ( $> 1000$ ). You can verify your algorithm by displaying the log-posterior curve.
- Start with small artificial images to see the correctness of your algorithm and to get a feeling for the parameters. Usually, it is recommended to test different powers of 10, i.e.,  $\sigma, \eta \in \{\dots, 10^{-1}, 10^0, 10^1, \dots\}$ .

## 4 A Different Prior

As we know from the lecture, a Gaussian distribution does not match the statistics of a natural image very well. A more appropriate distribution is the Student-t distribution:

$$f_H(T_{ij}, T_{i+1j}) = \left(1 + \frac{1}{2\sigma^2}(T_{i,j} - T_{i+1,j})^2\right)^{-\alpha} \quad (7)$$

**Tasks:** (5 points)

- Implement the gradient of this log-prior given above as `g = mrf_grad_log_student_prior(T, sigma, alpha)`. Do not forget the log in your partial derivatives.
- Evaluate your denoising algorithm with this new prior,  $\alpha = 1$  works fine. What do you observe?
- Display the gradient of the log-prior for the test images. Explain your results.

## 5 Independence Assumption

Finally, we question the assumption that the noise in each pixel is independent.

**Tasks:** (2 points)

- Is this assumption reasonable?
- What happens if you add spatially dependent noise to your image, e.g., a “noisy stripe“ like in old movies.
- Show results for both priors (Gaussian and Student-t distributions).

## 6 Bonus

(2 points) So far, we have used MRF-based image denoising for gray images only. How would you denoise a color image?